

# Datasheet for linear direct drive PPU-E35-Y-Axis and servo drive Indradrive Cs

Type of motor

PPU-E35-Y-Axis

Type of axis

PPU-E35-Y-Axis

Date of creation:

14.08.2024



Description	Symbol	Unit		comment
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## Electrical data

S-0-0141	Type of axis				
P-0-4014	Type of motor	Linear synchron motor		0200h	
P-0-0512	Temperature sensor			3	
	PWM frequency		kHz	4	
S-0-0111	Motor idle current (eff.)	$I_d$	A	1,8	
	Nominal motor force	$F_{nenn}$	N	147	with temperature increase of 65 K inside motor
	Power loss	Pconst	W	134	with temperature increase of 65 K inside motor
S-0-0109	Motor peak current (eff.)	$I_{max}$	A	8	
	Motor peak force	$F_{max}$	N	400	
S-0-0092	Bipolar force limit value		%	444,4	
P-0-0109	Force peak limit		%	444,4	
P-0-0051	Force constant	$k_t$	N/A	82	
	Motor constant	$K_m$	N/√W	12,7	
	BEMF (velocity 1 m/s)	$K_e$ (Phase-Phase)	V <sub>SS</sub>	110	
	Thermal resistance	R <sub>th</sub>	K/W	0,49	temperature increase (65 K) / Pconst
S-0-0113	Maximum motor speed	$v_{max}$	mm/min	120000	
	Max. frequency	$f_{max}$	Hz	71,2	
P-0-0018	Number of pole pairs per distance	PWT (Npol-Npol)	mm	28,1	
	Poles			7	
	Type of circuit			Y	
	Max. intermediate circuit voltage	U <sub>DC</sub>	V	900	
	Inductance	$L_{U-V}, L_{V-W}, L_{W-U}$	mH	250,00	
P-0-4016	Motor series inductance		mH	125,00	
P-0-4017	Motor shunt inductance		mH	125,00	
P-0-4048	Winding resistance by 25°C	$R_{U-V}, R_{V-W}, R_{W-U}$	Ohm	22,30	
	Winding resistance by 90°C	$R_{U-V}, R_{V-W}, R_{W-U}$	Ohm	28	
	Electrical time constant		ms	11,2	
	Type of temperature sensor		KTY		
S-0-0201	Motor warning temperature		°C	85	
S-0-0204	Motor shutdown temperature		°C	90	
	Insulation class		F		

## Mechanical Data

	Mass primary part without carriage	kg	0	
	Mass carriage	kg	0	
	Total mass primary part	kg	5	
	Total mass rail	kg/m	0	without attachments

## Control parameters without mass moment of inertia

S-0-0106	Current loop propotional gain		V/A	417
S-0-0107	Current loop integral action time		ms	14
S-0-0104	Position loop KV-Factor	kv		1
P-0-0004	Velocity loop smoothing time const.			900
S-0-0100	Velocity loop propotional gain	kp		0,012
S-0-0101	Velocity loop integral action time	TN		5

## Parameter of position

S-0-0277	Position feedback 1 type			1001 b
S-0-0278	Maximum travel range		mm	4000

## Encoder Feedback

	Measurement principle		magnetic	absolut magnetic	optic	
	Type of sensor		LE100	TTK 70	LIA22	
					Doubleflex	
	Tape measure		MB100	MBA 111	Slingflex	
	Manufacturer		SIKO	Sick Stegmann	Numerik	
	Grating period	μm	1000	1000	20	
	Supply voltage	V	5	7-12	5	
	Waveform		sin/cos	sin/cos / Hiperface	sin/cos	
	Reference mark		periodic	--	periodic	
	Reference mark pitch	mm	20	--	50	
	Signal amplitude	V <sub>SS</sub>	1	1	1	
S-0-0116 / S-0-0602.1.3	Feedback resolution	mm	1,00	1,00	0,02	

**Motor connection**

Connector	Connector	Contact
Tyco Electronic	U	thick 1
Typ: 923	V	thick 4
	W	thick 3
	GND	thick 2
Series connection of 3* temperature switch and KTY	Switch 105 °C ; PT1000	thin C thin D

**Thermal motor protection**

	Sensor1	Sensor2
Type	NTC	Switch
Type	PT1000	normally closed
Characteristic	Datasheet	105 °C

**Motor feedback**

Feedback	Signal	LE100 Sub D plug	TTK 70 Sub D plug	LIA22 Dub D plug	
	0V Sense	15			
	Ref - / EncData-	10	8	4	
	Ref + / EncData+	9	7	12	
	/B (COS-)	6	6	6	
	B(COS+)	5	5	14	
	A(SIN+)	2	2	13	
	/A(SIN-)	3	3	5	
	N.C.				
	GND (0V)	4	4	9	
	N.C.				
	Ucc	12	11	8	
	N.C.				
	GND (Schirm)				
	N.C.				
Adapter cable	ID	direct	direct	357798	